

TK-Tips: DSA Cheat Sheet – Part 1 (25 Concepts + Diagrams)



SECTION 1 — TIME & SPACE COMPLEXITY

1. Big-O Notation

Describes algorithm performance.

Common complexities:

$O(1) < O(\log n) < O(n) < O(n \log n) < O(n^2)$

Diagram:

$O(1)$: -----

$O(\log n)$: ----/////

$O(n)$: -----

$O(n \log n)$: ----////////

$O(n^2)$: //////////

2. Best, Average, Worst Case

Best: Ideal scenario

Avg: Expected performance

Worst: Maximum operations

3. Space Complexity

Memory consumed by algorithm including input + auxiliary space.

SECTION 2 — ARRAYS & STRINGS

4. Array Characteristics

Fixed size, index-based access $O(1)$.

Diagram:

[10][20][30][40][50]

5. Sliding Window Technique

Used for subarray problems like max sum, longest substring.

Diagram:

[L----R] → move window

6. Two Pointer Technique

Used for sorted arrays.

Diagram:

L → ← R

7. String Reversal

Two-pointer swap method.

8. Prefix Sum

Precompute cumulative sums.

Diagram:

arr: [1,2,3]

prefix: [1,3,6]

SECTION 3 — LINKED LISTS

9. Singly Linked List

Nodes pointing to next node.

Diagram:

[10]→[20]→[30]→NULL

10. Fast & Slow Pointer

Used for loops/middle element detection.

Diagram:

S→ F-----→

11. Reversing Linked List

Iterative pointer reversal.

12. Detect Loop (Floyd's Algorithm)

Slow + fast pointer.

Diagram:

S→ F→ (cycle)

13. Merge Two Sorted Lists

Use dummy node and merge step-by-step.

SECTION 4 — STACK AND QUEUE

14. Stack (LIFO)

push(), pop(), peek()

Diagram:

Top → [30]
[20]
[10]

15. Queue (FIFO)

enqueue(), dequeue()

Diagram:

Front→[10][20][30]←Rear

16. Monotonic Stack

Used for next greater element problems.

17. Circular Queue

Rear loops to front using modulo.

18. Min Stack

Stack with constant-time min retrieval.

SECTION 5 — TREES

19. Binary Tree

Each node has ≤ 2 children.

Diagram:

10
/\n5 20

20. Binary Search Tree (BST)

Left < Root < Right

21. Tree Traversals

Preorder, Inorder, Postorder, Level-order.

22. Height vs Depth

Height = longest path to leaf

Depth = distance from root

23. Balanced Tree

Height difference ≤ 1 everywhere.

SECTION 6 — GRAPHS & ALGORITHMS

24. BFS

Level-order traversal using queue.
Diagram:
Start → neighbors → next level

25. DFS

Recursive or stack-based traversal.
Diagram:
Deep path first.